

EXPLICIT SOLUTIONS OF THE MATRIX EQUATION $\sum A^i X D_i = C^*$

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Abstract. A module theoretic approach is developed to study the linear matrix equation $\sum A^i X D_i = C$. If the solution X is unique it can be expressed in the form $X = \sum A^k C G_k$. The matrices G_k can be determined from an auxiliary equation which involves the companion matrix of the characteristic polynomial of A . A connection is made with realizations of the inverse of the associated polynomial matrix $D(x) = \sum D_i x^i$. The more general equation $\sum A_i X D_i = C$ is discussed under the assumption that the matrices A_i are pairwise commutative.

Key words. linear matrix equations, Sylvester equations, realizations, simultaneous triangular form

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1. Introduction. Linear matrix equations have been studied since the time of Sylvester [10]. They are important in numerous applications (see, e.g., [5] with the regulator problem as a more recent example). An algebraic approach that originated with Kalman [7], [8] was elaborated by Djaferis and Mitter [1] to yield explicit solutions of equations of the form $\sum f_{ik} A^i X B^k = C$ (see also [12] and [13]). In this note, we adapt the module theoretic point of view of those papers and consider the more general equation

$$(1.1) \quad \sum_{i=0}^{p-1} A^i X D_i = C.$$

We first review some known facts concerning the equation

$$(1.2) \quad \sum_{i=0}^{p-1} \sum_{k=0}^{q-1} f_{ik} A^i X B^k = C,$$

which should direct us towards corresponding results on (1.1). All matrices in (1.1) and (1.2) are assumed to be complex, in particular, $A \in \mathbb{C}^{p \times p}$, $B, D_i \in \mathbb{C}^{q \times q}$, $C \in \mathbb{C}^{p \times q}$. Furthermore, the polynomial

$$f(x, y) = \sum \sum f_{ik} x^i y^k$$

is in $\mathbb{C}[x, y]$. For the results of this section, we refer to [1], [12], and [15].

Let $\lambda_1, \dots, \lambda_p$ be the eigenvalue of A and let

$$a(x) = a_0 + \dots + a_{p-1} x^{p-1} + x^p$$

be the characteristic polynomial of A . Define a companion matrix of $a(x)$ by

$$F_a = \begin{pmatrix} 0 & & & -a_0 \\ 1 & & & \vdots \\ & \ddots & & \vdots \\ & & 1 & -a_{p-1} \end{pmatrix}.$$

Let B have eigenvalues μ_1, \dots, μ_q and characteristic polynomial $b(x)$. The ideal in $\mathbb{C}[x, y]$ generated by $a(x)$ and $b(y)$ will be denoted by Ψ , i.e.,

$$\Psi = (a(x), b(y)).$$

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Equation (1.2) is called *universally solvable* if it has a solution for every C (which is necessarily unique).

For $h = \sum h_{ik}x^i y^k \in \mathbb{C}[x, y]$ and $M \in \mathbb{C}^{p \times q}$, let a product $h * M$ be defined by

$$h * M = \sum_{i,k} h_{ik} A^i M B^k.$$

The Cayley–Hamilton theorem implies that $d * M = 0$ for all $d \in \Psi$. Hence it is meaningful to define

$$(H + \Psi) * M = h * M$$

such that $\mathbb{C}^{p \times q}$ becomes a module over the ring $\mathbb{C}[x, y]/\Psi$. Then (1.2) can be written as $(f + \Psi) * X = C$.

THEOREM 1.1. *The following statements are equivalent:*

- (i) *Equation (1.2) is universally solvable.*
- (ii) *The following holds:*

$$(1.3) \quad f(\lambda_i, \mu_j) \neq 0 \quad \text{for } i = 1, \dots, p, \quad j = 1, \dots, q.$$

- (iii) *The element $f + \Psi$ is a unit of the ring $\mathbb{C}[x, y]/\Psi$.*
- (iv) *There exists a unique polynomial $g \in \mathbb{C}[x, y]$ such that*

$$(1.4) \quad fg \equiv 1 \pmod{\Psi}$$

and the degree of g in x is less than p and the degree in y is less than q .

- (v) *The equation*

$$(1.5) \quad \sum_{i=0}^{p-1} \sum_{k=0}^{q-1} f_{ik} F_a^i Y (F_b^T)^k = (1, 0, \dots, 0)_{1 \times p}^T (1, 0, \dots, 0)_{q \times 1}$$

is consistent.

Under condition (iii) above, the solution X can be expressed as $X = (f + \Psi)^{-1} * C$ and we have the following representation of X .

THEOREM 1.2. *If (1.2) is universally solvable and $g(x, y) = \sum g_{rs} x^r y^s$ is the polynomial given by (1.4), then*

$$(1.6) \quad X = \sum_{r=0}^{p-1} \sum_{s=0}^{q-1} g_{rs} A^r C B^s$$

is the solution of (1.2).

The polynomial g in (1.4) can be obtained from the auxiliary equation (1.5).

THEOREM 1.3. *Let $Y = G \in \mathbb{C}^{p \times q}$ be the solution of (1.5). Then*

$$g(x, y) = (1, x, \dots, x^{p-1}) G (1, y, \dots, y^{q-1})^T$$

is the polynomial with the properties of (iv) in Theorem 1.1.

The representation of X in (1.6) yields a bound for the rank of X . For $L \in \mathbb{C}^{p \times r}$ and $R \in \mathbb{C}^{r \times q}$, put

$$(1.7) \quad K(A, L) = (L, AL, \dots, A^{p-1}L)$$

and

$$D(B, R) = \begin{pmatrix} R \\ RB \\ \vdots \\ RB^{q-1} \end{pmatrix}.$$

THEOREM 1.4. *If (1.2) is universally solvable and if C is factorized as $C = LR$, then*

$$\text{rank } X \leq \min \{ \text{rank } K(A, L), \text{rank } D(B, R) \}.$$

2. An algebraic approach to explicit solutions. We now consider our target equation

$$(1.1) \quad \sum_{i=0}^{p-1} A^i X D_i = C.$$

Whether (1.1) is universally solvable or not depends on the eigenvalues λ_i of A and on a polynomial matrix $D \in \mathbb{C}^{q \times q}[x]$,

$$D(x) = \sum_{i=0}^{p-1} D_i x^i.$$

THEOREM 2.1 (see [2], [4], or [14]). *Equation (1.1) is solvable for all C if and only if*

$$(2.1) \quad \det D(\lambda_i) \neq 0 \quad \text{for } i = 1, \dots, p.$$

The left-hand side of (1.1) will be regarded as a product of X and D . For that purpose, let us define for $F = \sum F_i x^i \in \mathbb{C}^{q \times q}[x]$ and for $M \in \mathbb{C}^{p \times q}$ the operation

$$(2.2) \quad M * F = \sum A^i M F_i.$$

Then $\mathbb{C}^{p \times q}$ becomes a right module over the ring $\mathbb{C}^{q \times q}[x]$. Recall that $a(x)$ is the characteristic polynomial of A and put

$$\Phi = a(x)\mathbb{C}^{q \times q}[x]$$

such that Φ is the ideal in $\mathbb{C}^{q \times q}[x]$ generated by $a(x)I$. By the Cayley–Hamilton theorem, we have $M * H = 0$ for all $H \in \Phi$. Hence it makes sense to define

$$(2.3) \quad M * (F + \Phi) = M * F,$$

and it is easy to verify that $\mathbb{C}^{p \times q}$ together with the operation (2.3) is a unitary right module over the ring $\mathbb{C}^{q \times q}[x]/\Phi$. For a nonzero polynomial matrix $H = \sum_{i=0}^m H_i x^i$ with $H_m \neq 0$ we put $\text{deg } H = m$. In the case $H = 0$ we set $\text{deg } H = -\infty$. Obviously, in each coset $F + \Phi$ there is a unique representative of degree less than p , $p = \text{deg } a$.

Let us write (1.1) as

$$(2.4) \quad X * (D + \Phi) = C.$$

It is clear that (2.4) can be solved if $D + \Phi$ is invertible in $\mathbb{C}^{q \times q}[x]/\Phi$.

THEOREM 2.2. *The following statements (i) and (ii) are equivalent to condition (2.1) for the universal solvability of (1.1):*

- (i) $D + \Phi$ is a unit in the ring $\mathbb{C}^{q \times q}[x]/\Phi$.
- (ii) There exists a unique matrix $G \in \mathbb{C}^{q \times q}[x]$ such that

$$(2.5) \quad DG = GD \equiv I \pmod{\Phi}, \quad \text{deg } G < p.$$

Proof. We assume first that (2.1) holds. Then $d(x) = \det D$ and $a(x)$ have no zeros in common. Hence we have $a\gamma + d\delta = 1$ for some polynomials γ and δ . If $Q \in \mathbb{C}^{q \times q}[x]$ is the adjoint matrix of D , then $QD = DQ = dI$. Division of δQ by aI yields polynomial matrices B and G such that $\delta Q = aB + G$, $\text{deg } G < \text{deg } a = p$. From $\delta QD = D\delta Q = I - a\gamma I$ we see that G satisfies (2.5). The condition $\text{deg } G < p$ together with (2.5) assures that the matrix G in (2.5) is uniquely determined. Obviously, (ii) implies (i). Finally, if

(i) holds, then (1.1) is solvable and

$$(2.6) \quad X = C*(D + \Phi)^{-1}$$

is the unique solution. \square

From (2.6) we obtain the solution X in the following closed form.

THEOREM 2.3. *If (1.1) is universally solvable and*

$$(2.7) \quad G(x) = \sum_{i=0}^{p-1} G_i x^i$$

is the polynomial given by (2.5), then

$$(2.8) \quad X = \sum_{i=0}^{p-1} A^i C G_i$$

is the unique solution of (1.1).

The coefficient matrices G_i of (2.7) can be determined from an auxiliary equation which involves the companion matrix F_a of $a(x)$. For two matrices, $P = (p_{ij})$ and S , the Kronecker product is defined as $P \otimes S = (p_{ij}S)$. The identity matrix in (2.9) and (2.10) below is of size $q \times q$.

THEOREM 2.4. (i) *Let $G = \sum_{i=0}^{p-1} G_i x^i$ be given and put*

$$(2.9) \quad \tilde{G} = \begin{pmatrix} G_0 \\ G_1 \\ \vdots \\ G_{p-1} \end{pmatrix}, \quad E = \begin{pmatrix} I \\ 0 \\ \vdots \\ 0 \end{pmatrix}.$$

Then G satisfies $DG = GD \equiv I \pmod{\Phi}$ if and only if

$$(2.10) \quad \sum_{i=0}^{p-1} (F_a \otimes I)^i \tilde{G} D_i = E$$

holds.

(ii) *The equation*

$$\sum_{i=0}^{p-1} (F_a \otimes I)^i Y D_i = E$$

is consistent if and only if (2.1) holds.

Proof. (i) Because of $\deg a = p$, there exists a unique matrix $U = (I, Ix, \dots, Ix^{p-1}) \tilde{U} \in \mathbb{C}^{q \times q}[x]$, which satisfies $GD \equiv U \pmod{\Phi}$. We want to show that \tilde{U} is the matrix on the left-hand side of (2.10). Put $\tilde{x} = (1, x, \dots, x^{p-1})$. From $x^p = -a_0 - \dots - a_{p-1}x^{p-1} + a(x)$, we obtain

$$\tilde{x}x = (x, \dots, x^p) = \tilde{x}F_a + a(x)(0, \dots, 0, 1)$$

and $\tilde{x}x^i = \tilde{x}F_a^i + av_i$ for some $v_i \in \mathbb{C}^{1 \times p}[x]$. Because of $G = (\tilde{x} \otimes I)\tilde{G}$, we have

$$\begin{aligned} GD &= \sum_{i=0}^{p-1} (\tilde{x} \otimes I)x^i \tilde{G} D_i = \sum_{i=0}^{p-1} [(\tilde{x}F_a^i + av_i) \otimes I] \tilde{G} D_i \\ &= (\tilde{x} \otimes I) \sum_{i=0}^{p-1} (F_a \otimes I)^i \tilde{G} D_i + a \sum_{i=0}^{p-1} (v_i \otimes I) \tilde{G} D_i. \end{aligned}$$

Hence

$$\tilde{U} = \sum_{i=0}^{p-1} (F_a \otimes I)^i \tilde{G} D_i.$$

Clearly, $I = (\tilde{x} \otimes I)E$ and $U = (\tilde{x} \otimes I)\tilde{U}$. Therefore, $U = I$ is equivalent to (2.10). Theorem 2.4(ii) follows immediately from Theorem 2.2. \square

We consider now a particular case where $D(x)$ has only one invariant factor (different from 1). Put $e = (1, 0, \dots, 0)^T$, $e \in \mathbb{C}^p$.

THEOREM 2.5. *Assume that there exists a vector $v \in \mathbb{C}^{1 \times q}$ such that*

$$(2.11) \quad \text{rank} \begin{pmatrix} D(z) \\ v \end{pmatrix} = q \quad \text{for all } z \in \mathbb{C}.$$

Then the equation

$$(2.12) \quad \sum_{i=0}^{p-1} F_a^i Z D_i = ev$$

is consistent if and only if

$$(2.1') \quad \det D(\lambda_i) \neq 0$$

for all eigenvalues λ_i of F_a .

Proof. Clearly, (2.1) implies the solvability of (2.12). Suppose now that $\det D(\lambda) = 0$ for some eigenvalue λ of F_a and that (2.12) has a solution Z . Then there exists a vector $w = (w_1, \dots, w_q)^T$, $w \neq 0$, such that $D(\lambda)w = 0$ and a vector $u = (u_1, \dots, u_p)$, $u \neq 0$, such that

$$(2.13) \quad uF_a = \lambda u.$$

From

$$\begin{pmatrix} D(\lambda) \\ v \end{pmatrix} w = \begin{pmatrix} 0 \\ vw \end{pmatrix}$$

and (2.11) follows $vw \neq 0$, and (2.13) yields $u_1 \neq 0$. We multiply both sides of (2.12) by u and w . On the left-hand side we obtain

$$u(\sum F_a^i Z D_i)w = uZ(\sum \lambda^i D_i)w = uZD(\lambda)w = 0,$$

whereas on the right-hand side we have $u_1(vw) \neq 0$, which is a contradiction. Hence under the assumption (2.11) the condition (2.1) is also necessary for the consistency of (2.12). \square

To estimate the rank of the solution X of (1.1), we use the representation (2.8).

THEOREM 2.6. *Assume that (2.1) holds and let C be factorized as $C = LR$. Then*

$$\text{rank } X \leq \min \{ \text{rank } K(A, L), \text{rank } (I \otimes R)\tilde{G} \},$$

where $K(A, L)$ is defined by (1.7) and \tilde{G} is given by (2.9).

Proof. Write X in (2.8) as

$$X = (L, AL, \dots, A^{p-1}L) \begin{pmatrix} RG_0 \\ \vdots \\ RG_{p-1} \end{pmatrix} = K(A, L)(I \otimes R)\tilde{G}.$$

3. Realizations of D^{-1} . As its elements are rational functions, the matrix D^{-1} can be split into a proper rational and a polynomial part and thus be written as

$$(3.1) \quad D^{-1}(x) = K(Ix - F)^{-1}M + S(I - Nx)^{-1}T,$$

where N is nilpotent and the eigenvalues of F are zeros of $\det D$ (see, e.g., [9] or [6]). By a slight abuse of standard terminology, we will call a decomposition of the form (3.1) a *realization* of D^{-1} . Whenever a realization of D^{-1} is available, (1.1) can be reduced to a pair of equations of simpler type.

It will be convenient to express the solution of (1.1) by a contour integral.

THEOREM 3.1 [14]. *If the condition*

$$(2.1'') \quad \det \left(\sum \lambda_\nu D^\nu \right) = \det D(\lambda_\nu) \neq 0, \quad \nu = 1, \dots, p$$

holds, then the solution of (1.1) is given by

$$(3.2) \quad X = \frac{1}{2\pi i} \oint_\Gamma (Iz - A)^{-1}CD^{-1}(z)dz,$$

where Γ is a positively orientated simple closed curve such that all eigenvalues of A are interior to Γ and all zeros of $\det D(z)$ are exterior to Γ .

We single out two special equations.

COROLLARY 3.2. *Let $\lambda_1, \dots, \lambda_p$ and μ_1, \dots, μ_q be the eigenvalues of A and B , respectively.*

(i) *If $\lambda_i - \mu_j \neq 0$ for $i = 1, \dots, p, j = 1, \dots, q$, then*

$$(3.3) \quad AX - XB = C$$

has the unique solution

$$X = \frac{1}{2\pi i} \oint_\Gamma (Iz - A)^{-1}C(Iz - B)^{-1}dz,$$

where the λ_i 's are in the interior of Γ and the μ_j 's are outside of Γ .

(ii) *If $1 - \lambda_i\mu_j \neq 0$ for $i = 1, \dots, p, j = 1, \dots, q$, then*

$$(3.4) \quad X - AXB = C$$

has the unique solution

$$X = \frac{1}{2\pi i} \oint_\Gamma (Iz - A)^{-1}C(I - zB)^{-1}dz,$$

where all λ_i 's are inside of Γ and for $\mu_j \neq 0$ all the numbers μ_j^{-1} are outside of Γ .

If we replace D^{-1} in the integrand of (3.2) by the realization (3.1) and apply Corollary 3.2, we are led to equations of type (3.3) and (3.4).

THEOREM 3.3. *Assume that (2.1) holds and let (3.1) be a realization of D^{-1} . Then the solution of (1.1) is given by*

$$X = X_1M + X_2T$$

where X_1 and X_2 are the solutions of

$$AX_1 - X_1F = CK$$

and

$$X_2 - AX_2N = CS,$$

respectively.

4. A more general equation with commuting matrices. Let A_1, \dots, A_n be complex $p \times p$ matrices which are pairwise commutative. In this section, we outline an algebraic approach for the equation

$$(4.1) \quad \sum A_1^{i_1}, \dots, A_n^{i_n} X D_{i_1, \dots, i_n} = C.$$

We assume that the i_v 's are nonnegative integers and that the sum in (4.1) is finite. The matrices D_{i_1, \dots, i_n} are of size $q \times q$ and $C \in \mathbb{C}^{p \times q}$.

Pairwise commutativity implies that the matrices A_1, \dots, A_n can be simultaneously triangularized [3]. Hence for some nonsingular S we have

$$S^{-1}AS = \text{diag}(\lambda_{1i}, \dots, \lambda_{pi}) + N_i, \quad i = 1, \dots, n,$$

where the matrices N_i are upper triangular and nilpotent. The vectors $\lambda_j = (\lambda_{j1}, \dots, \lambda_{jn}), j = 1, \dots, p$, are called *joint eigentuples* of A_1, \dots, A_n . We associate (4.1) with a polynomial matrix $D \in \mathbb{C}^{q \times q}[y] = \mathbb{C}^{q \times q}[y_1, \dots, y_n]$, where D is given by

$$D = \sum D_{i_1, \dots, i_n} y_1^{i_1}, \dots, y_n^{i_n}.$$

It is well known (see, e.g., [11]) that (4.1) is universally solvable if and only if

$$(4.2) \quad \det D(\lambda_j) \neq 0$$

for all joint eigentuples λ_j of A_1, \dots, A_n .

Let γ be the ideal of those polynomials in $\mathbb{C}[y]$ that vanish on $\{\lambda_1, \dots, \lambda_p\}$,

$$\gamma = \bigcap_{j=1}^p (y_1 - \lambda_{j1}, \dots, y_n - \lambda_{jn}),$$

and let $\varphi \subseteq \mathbb{C}[y]$ be the ideal given by

$$\varphi = \{f \mid f \in \mathbb{C}[y], f(A_1, \dots, A_n) = 0\}.$$

Note that γ is determined by the semisimple part of the matrices A_i , whereas φ also involves the nilpotent parts. We have

$$\gamma^q \subseteq \varphi \subseteq \gamma,$$

which will allow us to work with γ^q instead of φ in what follows. We extend γ^q to an ideal Ψ in $\mathbb{C}^{q \times q}[y]$,

$$\Psi = \{hU \mid h \in \gamma^q, U \in \mathbb{C}^{q \times q}[y]\}.$$

For $F = \sum F_{k_1, \dots, k_n} y_1^{k_1}, \dots, y_n^{k_n} \in \mathbb{C}^{q \times q}[y]$ and $M \in \mathbb{C}^{p \times q}$, we define

$$(4.3) \quad M*(F + \Psi) = \sum A_1^{k_1}, \dots, A_n^{k_n} M F_{k_1, \dots, k_n}.$$

Then $\mathbb{C}^{p \times q}$ becomes a unitary right module over the ring $\mathbb{C}^{q \times q}[y]/\Psi$. Using Hilbert's Nullstellensatz, it can be shown that (4.2) holds if and only if $D + \Psi$ is a unit in $\mathbb{C}^{q \times q}[y]/\Psi$ or, equivalently, if there exists a matrix $G \in \mathbb{C}^{q \times q}[y]$ such that

$$(4.4) \quad DG = GD \equiv I \pmod{\Psi}.$$

If $G = \sum G_{k_1, \dots, k_n} y_1^{k_1}, \dots, y_n^{k_n}$ satisfies (4.4), then

$$X = \sum A_1^{k_1}, \dots, A_n^{k_n} C G_{k_1, \dots, k_n}$$

is the solution of (4.1).

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