

# Convergence Rates for Inverse Problems with Impulsive Noise

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# Outline

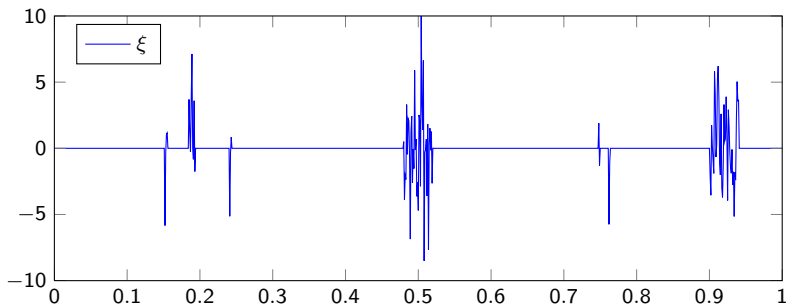
- ① Impulsive Noise
- ② Analysis of Tikhonov regularization
- ③ Application to Impulsive Noise
- ④ Numerical simulations
- ⑤ Conclusion

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- 1 Impulsive Noise
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# What is Impulsive Noise?

- noise  $\xi$  is small in large parts of the domain  $\mathbb{M}$ , but large on small parts of the domain
- occurs e.g. in digital image acquisition
- caused by faulty memory locations, malfunctioning pixels etc.
- popular example: salt-and-pepper noise



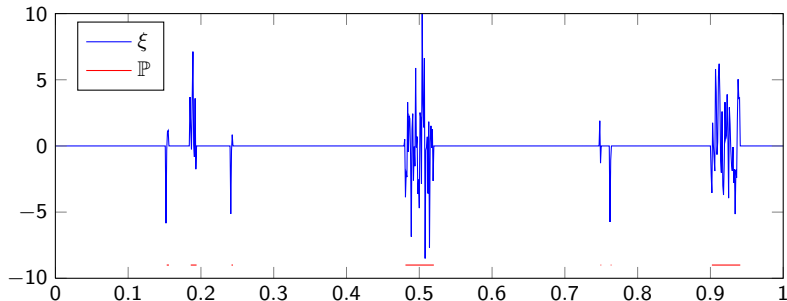
## A continuous model for impulsive noise

Suppose  $\xi \in \mathbf{L}^1(\mathbb{M})$ ,  $\mathfrak{B}(\mathbb{M}) \hat{=} \text{Borel } \sigma\text{-algebra of } \mathbb{M}$ .

### Noise model

There exist two parameters  $\varepsilon, \eta \geq 0$  such that

$$\exists \mathbb{P} \in \mathfrak{B}(\mathbb{M}) : \quad \|\xi\|_{\mathbf{L}^1(\mathbb{M} \setminus \mathbb{P})} \leq \varepsilon, \quad |\mathbb{P}| \leq \eta.$$



# Inverse Problems with Impulsive Noise

- we want to reconstruct  $f^\dagger$  from

$$g^{\text{obs}} = F(f^\dagger) + \xi =: g^\dagger + \xi$$

where  $\xi$  is impulsive noise

- natural setup:  $F : D(F) \subset \mathcal{X} \rightarrow \mathbf{L}^1(\mathbb{M}) \subseteq \mathcal{Y}$ , possibly nonlinear
- Favorable method: Tikhonov regularization

$$\hat{f}_\alpha \in \operatorname{argmin}_{f \in D(F)} \left[ \frac{1}{\alpha r} \left\| F(f) - g^{\text{obs}} \right\|_{\mathcal{Y}}^r + \mathcal{R}(f) \right]$$

- Minimizer  $\hat{f}_\alpha$  exists under reasonable assumptions.

## How to choose $\mathcal{Y}$ and $r$

here:  $F =$  linear integral operator (two times smoothing) on  $\mathbb{M} = [0, 1]$

$$f_{\alpha}^r = \operatorname{argmin}_{f \in \mathbf{L}^2(\mathbb{M})} \left[ \frac{1}{r\alpha} \left\| F(f) - g^{\text{obs}} \right\|_{\mathbf{L}^r(\mathbb{M})}^r + \|f\|_{\mathbf{L}^2(\mathbb{M})}^2 \right], \quad r = 1, 2$$

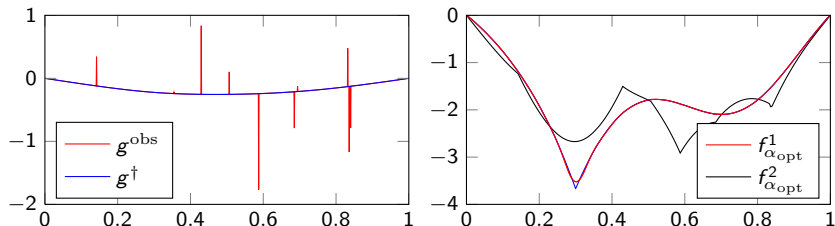
computation of  $f_{\alpha}^1$  via dual formulation, see e.g.



C. Clason, B. Jin, K. Kunisch.

A semismooth Newton method for  $\mathbf{L}^1$  data fitting with automatic choice of regularization parameters and noise calibration.

*SIAM J. Imaging Sci.*, 3:199–231, 2010.



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## Theoretical state of the art

- known theory provides rates of convergence as  $\|\xi\|_{\mathcal{Y}}$  tends to 0
- this does not fully explain the remarkable quality of the  $\mathbf{L}^1$ -reconstruction!

Example: 'Most impulsive' noise.  $\mathcal{Y} = \mathfrak{M}(\mathbb{M})$  (space of all signed measures) and

$$\xi = \sum_{j=1}^N c_j \delta_{x_j}$$

with  $N \in \mathbb{N}$ ,  $c_j \in \mathbb{R}$  and  $x_j \in \mathbb{M}$  for  $1 \leq j \leq N$ .

Then  $\|\xi\|_{\mathfrak{M}(\mathbb{M})} = \sum_{j=1}^N |c_j|$  might be large! However

$$\|g - g^{\text{obs}}\|_{\mathfrak{M}(\mathbb{M})} = \|g - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} + \sum_{j=1}^N |c_j| = \|g - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} + \|\xi\|_{\mathfrak{M}(\mathbb{M})}.$$

So  $\xi$  does not influence the minimizer  $\hat{f}_\alpha$ !

## Improving the noise level

'Most impulsive' noise  $\xi$  influences  $g \mapsto \|g - g^{\text{obs}}\|_{\mathfrak{M}(\mathbb{M})}$  only as an additive constant, no influence on  $\widehat{f}_\alpha$ !

Idea: For general  $\xi$  study the influence of  $\xi$  on the data fidelity term  $\|g - g^{\text{obs}}\|_{\mathcal{Y}}^r$  for all  $g$ .

### Variational noise assumption

Suppose there exist  $C_{\text{err}} > 0$  and a noise level function  $\text{err} : F(D(F)) \rightarrow [0, \infty]$  such that

$$\|g - g^{\text{obs}}\|_{\mathcal{Y}}^r - \|\xi\|_{\mathcal{Y}}^r \geq \frac{1}{C_{\text{err}}} \|g - g^\dagger\|_{\mathcal{Y}}^r - \text{err}(g), \quad g \in F(D(F)).$$

Examples for the noise function **err**

$$\left\| g - g^{\text{obs}} \right\|_{\mathcal{Y}}^r - \|\xi\|_{\mathcal{Y}}^r \geq \frac{1}{C_{\text{err}}} \left\| g - g^\dagger \right\|_{\mathcal{Y}}^r - \mathbf{err}(g), \quad g \in F(D(F)).$$

- ① It follows from the triangle inequality that the Assumption is always fulfilled with

$$C_{\text{err}} = 2^{r-1} \quad \text{and} \quad \mathbf{err} \equiv 2 \|\xi\|_{\mathcal{Y}}^r.$$

- ② In the Example of 'most impulsive' noise ( $\mathcal{Y} = \mathfrak{M}(\mathbb{M})$ ,  $r = 1$ ) the Assumption holds true with the optimal parameters

$$C_{\text{err}} = 1 \quad \text{and} \quad \mathbf{err} \equiv 0.$$

# Convergence analysis under the variational noise assumption

- **Bregman distance:**

$$D_{\mathcal{R}}^{f^*} (f, f^\dagger) := \mathcal{R}(f) - \mathcal{R}(f^\dagger) - \langle f^*, f - f^\dagger \rangle$$

where  $f^* \in \partial \mathcal{R}(f^\dagger) \subset \mathcal{X}'$ .

- use a **variational inequality** as source condition:

$$\beta D_{\mathcal{R}}^{f^*} (f, f^\dagger) \leq \mathcal{R}(f) - \mathcal{R}(f^\dagger) + \varphi \left( \|F(f) - g^\dagger\|_{\mathcal{Y}}^r \right)$$

for all  $f \in D(F)$  with  $\beta > 0$ .  $\varphi$  is assumed to fulfill

- $\varphi(0) = 0$ ,
- $\varphi \nearrow$ ,
- $\varphi$  concave.

## Convergence rates

suppose

- the noise assumption is fulfilled with a function  $\mathbf{err} \geq 0$  and
- the variational inequality holds true.

### Theorem (error decomposition)

$$\beta \mathcal{D}_{\mathcal{R}}^{f^*}(\hat{f}_\alpha, f^\dagger) \leq \frac{\mathbf{err}(F(\hat{f}_\alpha))}{r\alpha} + (-\varphi)^* \left( -\frac{1}{rC_{\text{err}}\alpha} \right),$$

$$\|F(\hat{f}_\alpha) - g^\dagger\|_{\mathcal{Y}}^r \leq \frac{C_{\text{err}}}{\lambda} \mathbf{err}(F(\hat{f}_\alpha)) + \frac{rC_{\text{err}}\alpha}{\lambda} (-\varphi)^* \left( -\frac{1-\lambda}{rC_{\text{err}}\alpha} \right)$$

for all  $\alpha > 0$  and  $\lambda \in (0, 1)$ .

Fenchel conjugate:

$$(-\varphi)^*(s) = \sup_{\tau \geq 0} (s\tau + \varphi(\tau)).$$

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## Working schedule

- consider Tikhonov regularization for Inverse Problems with Impulsive Noise ( $\mathcal{Y} = \mathbf{L}^1(\mathbb{M})$ ,  $r = 1$ ):

$$\hat{f}_\alpha \in \operatorname{argmin}_{f \in D(F)} \left[ \frac{1}{\alpha} \left\| F(f) - g^{\text{obs}} \right\|_{\mathbf{L}^1(\mathbb{M})} + \mathcal{R}(f) \right]$$

- recall: noise  $\xi$  fulfills

$$\exists \mathbb{P} \in \mathfrak{B}(\mathbb{M}) : \quad \|\xi\|_{\mathbf{L}^1(\mathbb{M} \setminus \mathbb{P})} \leq \varepsilon, \quad |\mathbb{P}| \leq \eta$$

$\rightsquigarrow$  need to estimate  $\mathbf{err}(g)$  with  $g = F(\hat{f}_\alpha)$  defined by

$$\left\| g - g^{\text{obs}} \right\|_{\mathbf{L}^1(\mathbb{M})} - \|\xi\|_{\mathbf{L}^1(\mathbb{M})} \geq \frac{1}{C_{\text{err}}} \left\| g - g^\dagger \right\|_{\mathbf{L}^1(\mathbb{M})} - \mathbf{err}(g)$$

## First step: triangle inequalities

$$\|g - g^{\text{obs}}\|_{\mathbf{L}^1(\mathbb{M})} - \|\xi\|_{\mathbf{L}^1(\mathbb{M})} \geq \frac{1}{C_{\text{err}}} \|g - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} - \text{err}(g)$$

$$\begin{aligned} \|g - g^{\text{obs}}\|_{\mathbf{L}^1(\mathbb{M})} - \|\xi\|_{\mathbf{L}^1(\mathbb{M})} &= \int_{\mathbb{M} \setminus \mathbb{P}} [ |g^{\text{obs}} - g| - |\xi| ] \, dx + \int_{\mathbb{P}} [ |g^{\text{obs}} - g| - |\xi| ] \, dx \\ &\geq \|g - g^\dagger\|_{\mathbf{L}^1(\mathbb{M} \setminus \mathbb{P})} - 2\varepsilon - |\mathbb{P}| \|g - g^\dagger\|_{\mathbf{L}^\infty(\mathbb{P})} \\ &\geq \|g - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} - 2\varepsilon - 2\eta \|g - g^\dagger\|_{\mathbf{L}^\infty(\mathbb{P})} \end{aligned}$$

Here we used

- the first triangle inequality on  $\mathbb{M} \setminus \mathbb{P}$  and
- the second triangle inequality on  $\mathbb{P}$ .



## Second step: improving the bound

$$\|g - g^{\text{obs}}\|_{\mathbf{L}^1(\mathbb{M})} - \|\xi\|_{\mathbf{L}^1(\mathbb{M})} \geq \|g - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} - 2\varepsilon - 2\eta \|g - g^\dagger\|_{\mathbf{L}^\infty(\mathbb{P})}$$

If  $F$  is smoothing and  $g = F(f)$ , then  $\|g - g^\dagger\|_{\mathbf{L}^\infty(\mathbb{P})}$  also decays with  $\eta$ !

### Theorem (Hohage, W.)

If  $k > d/p$ , then for all  $C_{\text{err}} > 1$  there exist  $C > 0$  and  $\eta_0 > 0$  such that

$$\|v\|_{\mathbf{L}^\infty(\mathbb{M})} \leq C\eta^{\frac{k}{d} - \frac{1}{p}} |v|_{W^{k,p}(\mathbb{M})} + \frac{C_{\text{err}} - 1}{2C_{\text{err}}\eta} \|v\|_{\mathbf{L}^1(\mathbb{M})}$$

for all  $v \in W^{k,p}(\mathbb{M})$  and  $\eta \in (0, \eta_0]$ .

Follows from techniques used in approximation theory / FEM analysis (Ehrling's lemma and Sobolev's embedding theorem).

## Second step: improving the bound (cont')

### Smoothing assumption on $F$

$\mathbb{M} \subset \mathbb{R}^d$  bounded & Lipschitz,  $\exists k \in \mathbb{N}_0, p \in [1, \infty], k > d/p$  and  $q \in (1, \infty)$  such that

$$F(D(F)) \subset W^{k,p}(\mathbb{M}) \quad \text{and} \quad \left| F(f) - g^\dagger \right|_{W^{k,p}(\mathbb{M})} \leq C_{F,k,p} \mathcal{D}_{\mathcal{R}}^{f*}(f, f^\dagger)^{\frac{1}{q}}$$

for all  $f \in D(F)$  with some  $C_{F,k,p} > 0$ .

This allows us to use  $v = F(f) - g^\dagger$ , e.g. it follows

$$\|F(f) - g^\dagger\|_{L^\infty(\mathbb{M})} \leq C\eta^{\frac{k}{d} - \frac{1}{p}} \|F(f) - g^\dagger\|_{W^{k,p}(\mathbb{M})} + \frac{C_{\text{err}} - 1}{2C_{\text{err}}\eta} \|F(f) - g^\dagger\|_{L^1(\mathbb{M})}$$

whenever  $\eta$  is sufficiently small.

## Second step: improving the bound (cont')

$$\begin{aligned}
& \|F(f) - g^{\text{obs}}\|_{\mathbf{L}^1(\mathbb{M})} - \|\xi\|_{\mathbf{L}^1(\mathbb{M})} \\
& \geq \|F(f) - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} - 2\varepsilon - 2\eta \|F(f) - g^\dagger\|_{\mathbf{L}^\infty(\mathbb{P})} \\
& \geq \left(1 - \frac{C_{\text{err}} - 1}{C_{\text{err}}}\right) \|F(f) - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} - 2\varepsilon - 2C\eta^{\frac{k}{d} - \frac{1}{p} + 1} \|F(f) - g^\dagger\|_{W^{k,p}(\mathbb{M})} \\
& \geq \frac{1}{C_{\text{err}}} \|F(f) - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} - 2\varepsilon - 2CC_{F,k,p}\eta^{\frac{k}{d} - \frac{1}{p} + 1} \mathcal{D}_{\mathcal{R}}^{f^*}(f, f^\dagger)^{\frac{1}{q}} \\
& \stackrel{!}{\geq} \frac{1}{C_{\text{err}}} \|F(f) - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} - \mathbf{err}(F(f))
\end{aligned}$$

$$\begin{aligned}
\|F(f) - g^\dagger\|_{\mathbf{L}^\infty(\mathbb{M})} & \leq C\eta^{\frac{k}{d} - \frac{1}{p}} \|F(f) - g^\dagger\|_{W^{k,p}(\mathbb{M})} + \frac{C_{\text{err}} - 1}{2C_{\text{err}}\eta} \|F(f) - g^\dagger\|_{\mathbf{L}^1(\mathbb{M})} \\
& \|F(f) - g^\dagger\|_{W^{k,p}(\mathbb{M})} \leq C_{F,k,p} \mathcal{D}_{\mathcal{R}}^{f^*}(f, f^\dagger)^{\frac{1}{q}}
\end{aligned}$$

Thus for any  $C_{\text{err}} > 1$  we can choose

$$\mathbf{err}(F(f)) = 2\varepsilon + 2C_{\text{err}}\eta^{\frac{k}{d} - \frac{1}{p} + 1} C_{F,k,p} \mathcal{D}_{\mathcal{R}}^{f^*}(f, f^\dagger)^{\frac{1}{q}}$$

### Third step: final estimate for $\mathbf{err} \left( F \left( \widehat{f}_\alpha \right) \right)$

Calculation above:

$$\mathbf{err} \left( F \left( \widehat{f}_\alpha \right) \right) = 2\varepsilon + 2C_{F,k,p} C \eta^{\frac{k}{d} - \frac{1}{p} + 1} \mathcal{D}_{\mathcal{R}}^{f^*} \left( \widehat{f}_\alpha, f^\dagger \right)^{\frac{1}{q}}$$

General convergence analysis:

$$\beta \mathcal{D}_{\mathcal{R}}^{f^*} \left( \widehat{f}_\alpha, f^\dagger \right) \leq \frac{\mathbf{err} \left( F \left( \widehat{f}_\alpha \right) \right)}{\alpha} + (-\varphi)^* \left( -\frac{1}{C_{\text{err}} \alpha} \right)$$

This implies using Young's inequality and  $(a + b)^{\frac{1}{q}} \leq a^{\frac{1}{q}} + b^{\frac{1}{q}}$  that

$$\mathbf{err} \left( F \left( \widehat{f}_\alpha \right) \right) \leq 2q'\varepsilon + (q' - 1) \eta^{\frac{q'k}{d} + \frac{q'(p-1)}{p}} \frac{1}{\alpha^{q'-1}} + C' (-\varphi)^* \left( -\frac{1}{C_{\text{err}} \alpha} \right)$$

where  $1/q + 1/q' = 1$  and  $C' > 0$  whenever  $\alpha > 0$  and  $\eta \geq 0$  is sufficiently small.

## Error bound for Tikhonov regularization

Insert the estimate for  $\mathbf{err} \left( F \left( \widehat{f}_\alpha \right) \right)$  into the general error decomposition to obtain

### Theorem (Hohage, W.)

Suppose the variational inequality is fulfilled and  $F$  obeys the smoothing assumption. Then we have for arbitrary  $C_{\text{err}} > 1$  and all  $\alpha > 0$  and  $\eta > 0$  sufficiently small

$$\beta \mathcal{D}_{\mathcal{R}}^{f^*} \left( \widehat{f}_\alpha, f^\dagger \right) \leq 2q' \frac{\varepsilon}{\alpha} + (q' - 1) \frac{\eta^{\frac{q'k}{d} + \frac{q'(p-1)}{p}}}{\alpha^{q'}} + C' (-\varphi)^* \left( -\frac{1}{C_{\text{err}} \alpha} \right)$$

$$\left\| F \left( \widehat{f}_\alpha \right) - g^\dagger \right\|_{\mathbf{L}^1(\mathbb{M})} \leq 4q' \varepsilon + 2(q' - 1) \frac{\eta^{\frac{q'k}{d} + \frac{q'(p-1)}{p}}}{\alpha^{q'-1}} + 2C' C_{\text{err}} \alpha (-\varphi)^* \left( -\frac{1}{C_{\text{err}} \alpha} \right)$$

For simplicity we study only  $q = 2$  and  $\varphi(\tau) = c\tau^\kappa$  with  $c > 0$  and  $\kappa \in (0, 1)$  in the following.

## An optimal a priori parameter choice

$$\beta \mathcal{D}_{\mathcal{R}}^{f^*}(\widehat{f}_{\alpha}, f^{\dagger}) \leq 4 \frac{\varepsilon}{\alpha} + \frac{\eta^{\frac{2k}{d} + \frac{2(p-1)}{p}}}{\alpha^2} + C' (-\varphi)^* \left( -\frac{1}{C_{\text{err}} \alpha} \right)$$

If  $\varphi(t) = c \cdot t^{\kappa}$  with  $c > 0$  and  $\kappa \in (0, 1)$ , then  $(-\varphi)^* \left( -\frac{1}{\alpha} \right) = C \cdot \alpha^{\frac{\kappa}{1-\kappa}}$ .

So for  $\alpha \sim \max \left\{ \varepsilon^{1-\kappa}, \eta^{\left(\frac{1-\kappa}{2-\kappa}\right) \left(\frac{2k}{d} + \frac{2(p-1)}{p}\right)} \right\}$  we obtain

$$\mathcal{D}_{\mathcal{R}}^{f^*}(\widehat{f}_{\alpha}, f^{\dagger}) = \mathcal{O} \left( \max \left\{ \varepsilon^{\kappa}, \eta^{\frac{\kappa \gamma}{2-\kappa}} \right\} \right)$$

with  $\gamma := \frac{2k}{d} + \frac{2(p-1)}{p}$  as  $\max \{ \varepsilon, \eta \} \searrow 0$ .

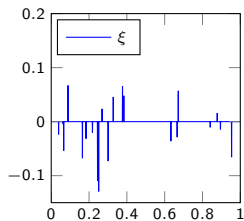
# Functional dependence of $\varepsilon$ and $\eta$

$$\exists \mathbb{P} \in \mathfrak{B}(\mathbb{M}) : \quad \|\xi\|_{\mathbf{L}^1(\mathbb{M} \setminus \mathbb{P})} \leq \varepsilon, \quad |\mathbb{P}| \leq \eta \quad (1)$$

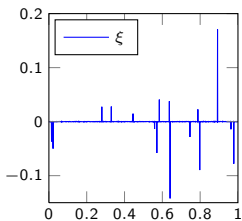
- model allows for different choices of  $\varepsilon$  and  $\eta$  which depend on each other
- study the dependence function

$$\varepsilon_\xi(\eta) := \inf \left\{ \|\xi\|_{\mathbf{L}^1(\mathbb{M} \setminus \mathbb{P})} \mid \mathbb{P} \in \mathfrak{B}(\mathbb{M}), |\mathbb{P}| \leq \eta \right\} .$$

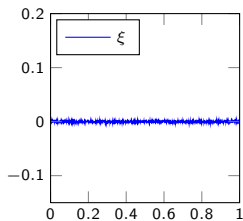
- then for any  $\eta \geq 0$  eq. (1) is fulfilled with  $\varepsilon = \varepsilon_\xi(\eta)$
- for  $\xi \in \mathbf{L}^1(\mathbb{M})$  the following holds true:
  - 1  $\varepsilon_\xi(0) = \|\xi\|_{\mathbf{L}^1(\mathbb{M})}$ ,  $\varepsilon_\xi(|\mathbb{M}|) = 0$
  - 2  $\varepsilon_\xi$  is continuous, decreasing, and convex

Examples for  $\varepsilon_\xi$ 

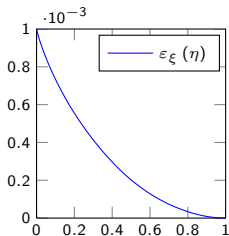
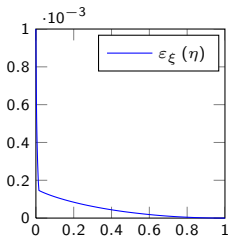
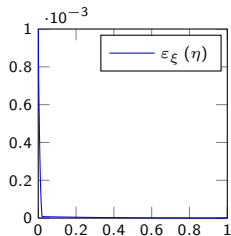
Impulsive noise



Impulsive noise?



Gaussian white noise





## Convergence rates in terms of an optimal $\eta$

- Recall:  $\mathcal{D}_{\mathcal{R}}^{f^*}(\widehat{f}_\alpha, f^\dagger) = \mathcal{O}\left(\max\left\{\varepsilon^\kappa, \eta^{\frac{\kappa\gamma}{2-\kappa}}\right\}\right)$
- Substituting  $\varepsilon$  by  $\varepsilon_\xi(\eta)$  yields

$$\mathcal{D}_{\mathcal{R}}^{f^*}(\widehat{f}_\alpha, f^\dagger) \leq C \inf_{0 \leq \eta \leq |\mathbb{M}|} \left[ \varepsilon_\xi(\eta)^\kappa + \eta^{\frac{\kappa}{2-\kappa}\gamma} \right] \quad \text{as } \xi \rightarrow 0$$

- Note that  $\xi$  and  $\varepsilon_\xi$  are unknown in general, but possibly an upper bound for  $\varepsilon_\xi$  can be calculated
- As  $\varepsilon_\xi \searrow$  and  $\eta^{\frac{\kappa}{2-\kappa}\gamma} \nearrow$  in  $\eta$ , there exists an intersecting point  $\bar{\eta} > 0$
- Thus we have

$$\mathcal{D}_{\mathcal{R}}^{f^*}(\widehat{f}_\alpha, f^\dagger) \leq 2C\varepsilon_\xi(\bar{\eta})^\kappa \quad \text{as } \xi \rightarrow 0$$

- The state-of-the-art analysis yields ( $\eta = 0$ )

$$\mathcal{D}_{\mathcal{R}}^{f^*}(\widehat{f}_\alpha, f^\dagger) \leq \tilde{C}\varepsilon_\xi(0)^\kappa \quad \text{as } \xi \rightarrow 0.$$

↪ improvement measured by the factor  $(\varepsilon_\xi(0)/\varepsilon_\xi(\bar{\eta}))^\kappa$ , **which is arbitrary large for impulsive noise**

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## Considered operator

- $\mathbb{M} = [0, 1]$  and  $T : \mathbf{L}^2(\mathbb{M}) \rightarrow \mathbf{L}^2(\mathbb{M})$  defined by

$$(Tf)(x) = \int_0^1 k(x, y) f(y) dy, \quad x \in \mathbb{M}$$

with kernel  $k(x, y) = \min\{x \cdot (1 - y), y \cdot (1 - x)\}$ ,  $x, y \in \mathbb{M}$ .

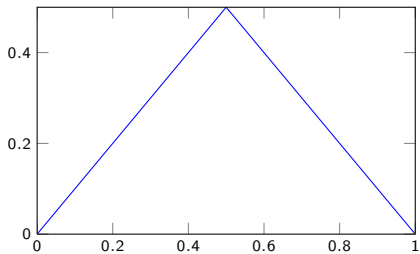
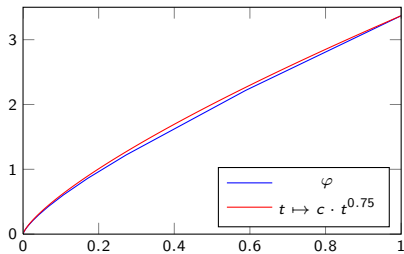
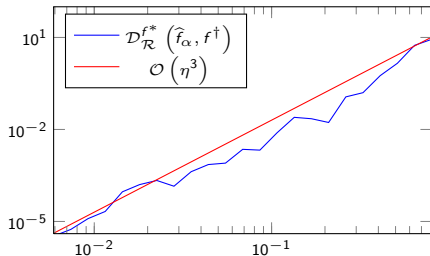
- then  $(Tf)'' = f$  for any  $f \in \mathbf{L}^2(\mathbb{M})$  and  $T$  is 2 times smoothing ( $k = 2$  and  $p = 2$ ).
- the smoothing Assumption is valid with exponent  $\gamma = 2k/d + 2(p - 1)/p = 5$  and  $q = 2$
- discretization: equidistant points  $x_1 = \frac{1}{2n}, x_2 = \frac{3}{2n}, \dots, x_n = \frac{2n-1}{2n}$  and composite midpoint rule

$$(Tf)(x) = \int_0^1 k(x, y) f(y) dy \approx \frac{1}{n} \sum_{i=1}^n k(x, x_i) f(x_i).$$

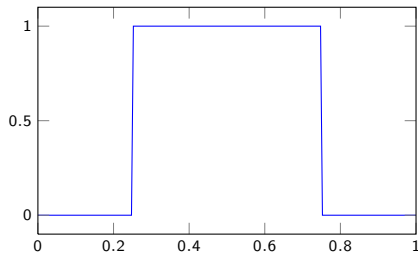
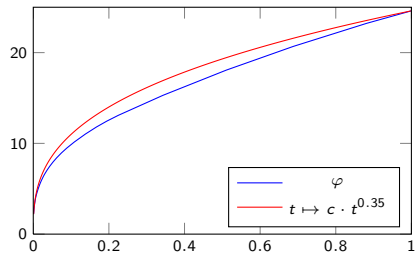
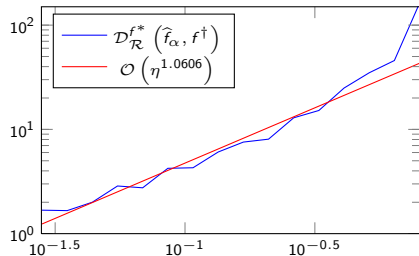
# Simulations

- $f^\dagger$  and  $g^\dagger$  are calculated analytically to avoid an inverse crime
- we consider 'purely impulsive noise' ( $\varepsilon = 0$ ) for different values of  $\eta$
- generation of  $\xi$ :
  - given  $\eta$ , choose randomly  $\lceil \eta \cdot n \rceil$  grid points forming  $\mathbb{P}$
  - simulate  $\xi$  such that  $\xi_{|_{M \setminus \mathbb{P}}} = 0$  and  $\xi_{|\mathbb{P}} = \pm 1/\eta$  with probability 1/2 respectively for each  $x_j \in \mathbb{P}$
- for each  $\eta_j = (4/5)^j$ ,  $j = 1, \dots$  we perform 10 experiments
- in each experiment  $\alpha$  is chosen optimally by trial and error
- following plots show  $\eta$  vs. empirical mean of  $\mathcal{D}_{\mathcal{R}}^{f^*}(\hat{f}_\alpha, f^\dagger)$

## Example 1

(a) Exact solution  $f^\dagger$ (b) Estimated index function  $\varphi$ (c) mean convergence in  $\mathcal{X}$

## Example 2

(d) Exact solution  $f^\dagger$ (e) Estimated index function  $\varphi$ (f) mean convergence in  $\mathcal{X}$

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- ① Impulsive Noise
- ② Analysis of Tikhonov regularization
- ③ Application to Impulsive Noise
- ④ Numerical simulations
- ⑤ Conclusion

## Presented results and future work

- Inverse Problems with Impulsive noise
  - continuous model for Impulsive noise
  - improved convergence rates
- numerical examples suggest order optimality
- future work: infinitely smoothing operators!



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Convergence rates for Inverse Problems with Impulsive Noise.

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Thank you for your attention!